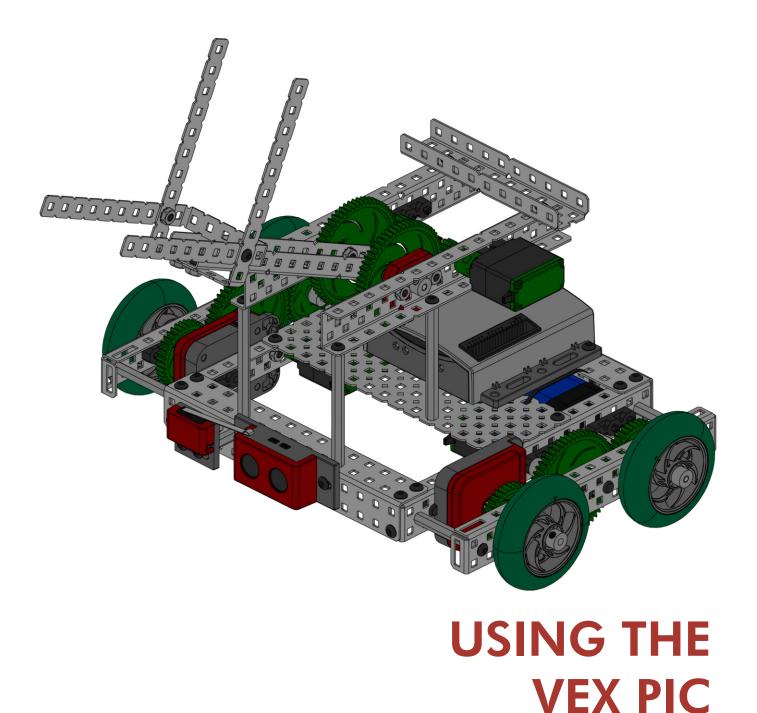


RECBOT BUILDING INSTRUCTIONS



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RECBOT BUILDING INSTRUCTIONS



Collect parts and tools from the lists below:

Materials	Quantity
Screw, 8-32 x 1/4″ Long	42
Screw, 8-32 x 1/2" Long	6
Screw, 8-32 x 3/8" Long	9
Motor Screw, Long [1/2"]	6
Nut, 8-32 Keps	37
Shaft, 3″ long	6
Shaft, 2″ long	2
Shaft Collar	17
4.6mm Plastic Spacer	10
Bearing, Flat	15
Bearing Pop Rivets	24
Standoff, 3″ Long	4
Standoff, 2″ Long	4
Standoff, 1″ Long	2
Gear, 12 tooth	2
Gear, 36 tooth	4
Gear, 60 tooth	4
Chassis Rail, 16 hole	4
Chassis Bumper, 15 hole	2
C-Channel, 1x2x1x15 hole	2
C-Channel, 1x2x1x25 hole	1
Plate, 5 x 15 hole	1
Bar, 25 hole	2
Small Low Friction VEX Wheel	4
VEX Microcontroller*	1
VEX Motor w/ Clutch	3
7.2V Robot Battery*	1
Optical Shaft Encoder*	2
Limit Switch*	1
Ultrasonic Rangefinder*	1
Potentiometer*	1
RF Receiver Module*	1
Receiver Antenna Sleeve*	1
Receiver Antenna Sleeve Holder*	1

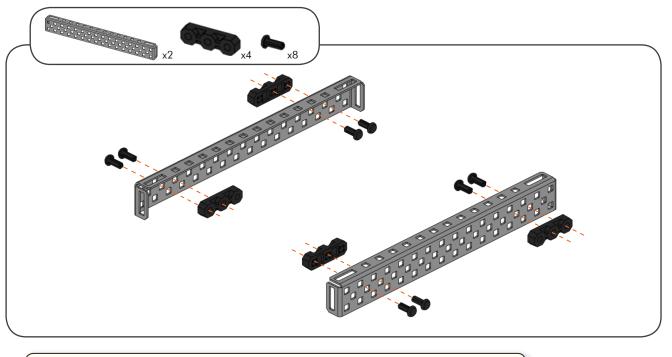
Tools	Quantity
Zip Tie, 4″ Long	4
Allen Wrench 3/32"	1
Allen Wrench 5/64″	1
Open End Wrench 1/4"	1
Pliers*	1
Hacksaw*	1
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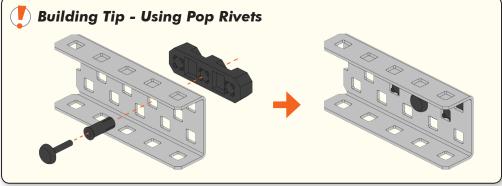
* Not included in Protobot Robot Kit

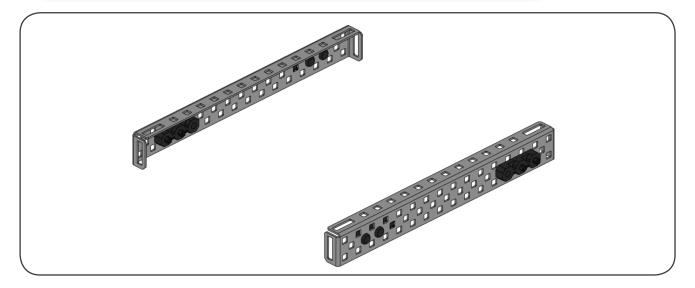




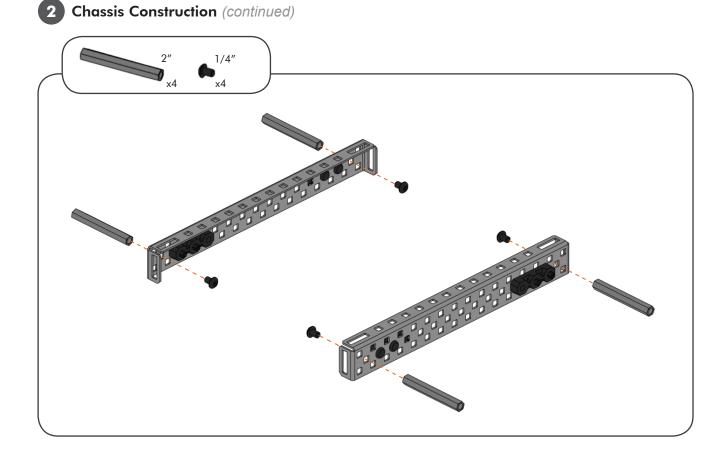
Chassis Construction

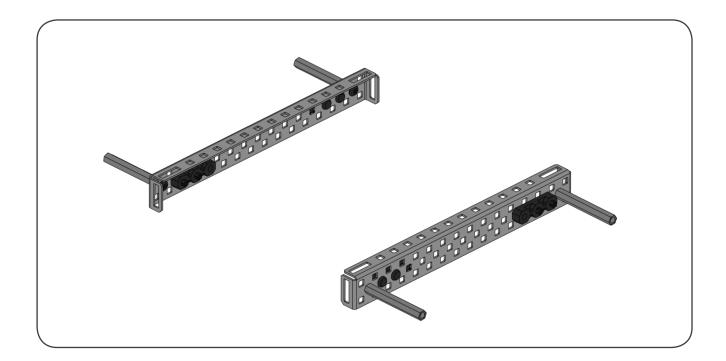




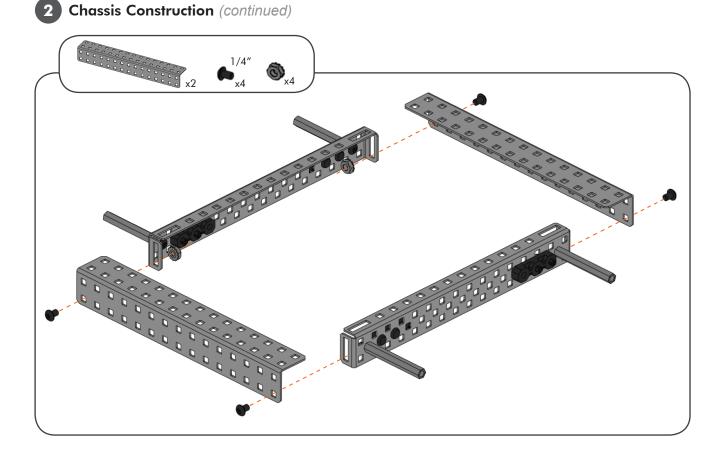


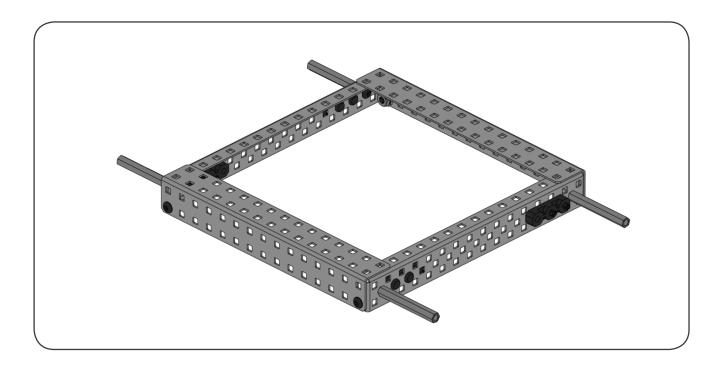
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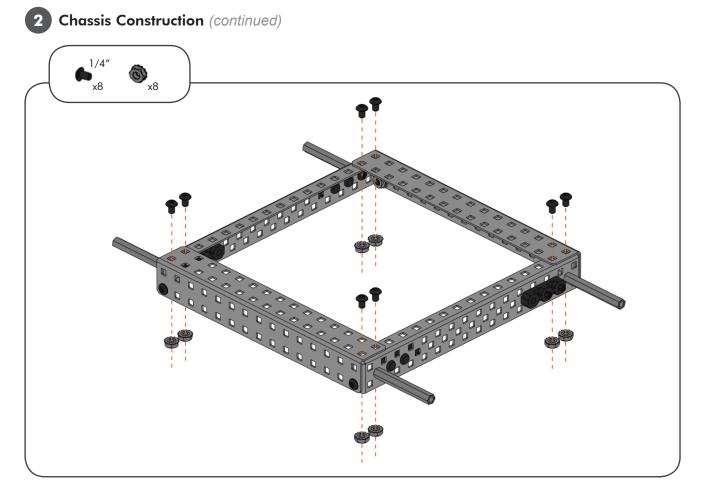


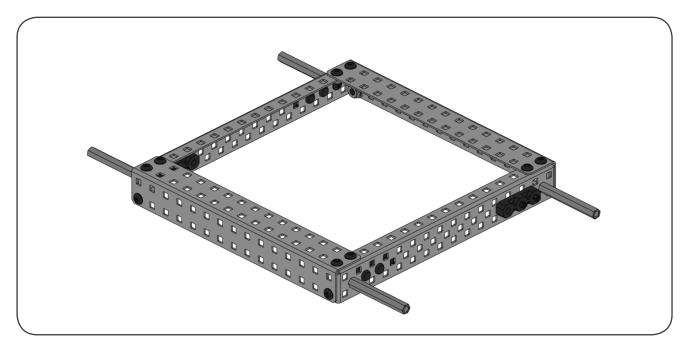






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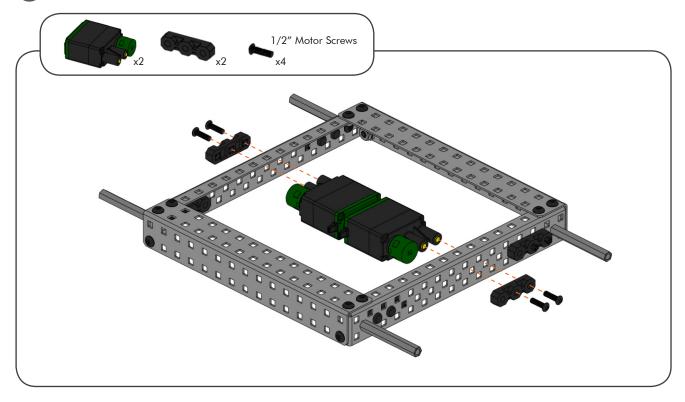


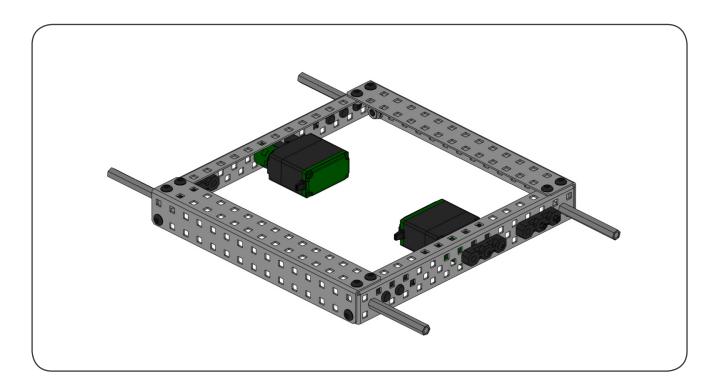


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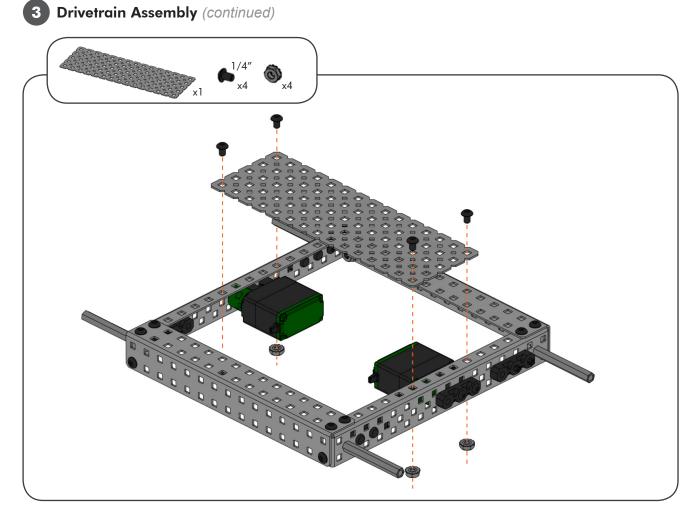


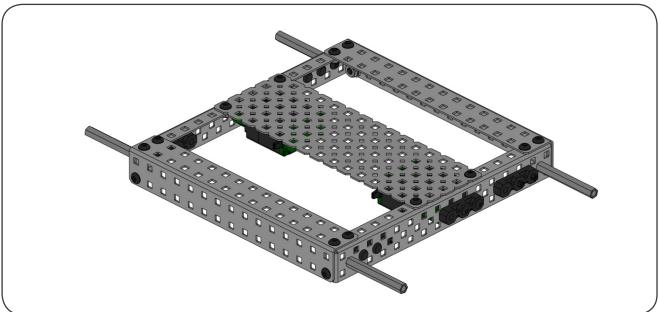
3 Drivetrain Assembly



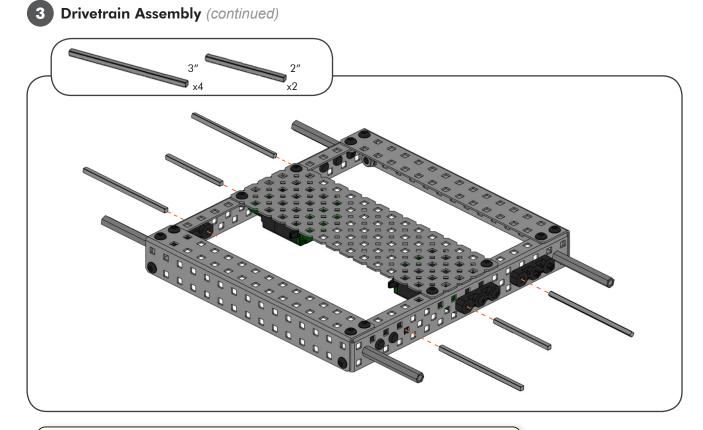






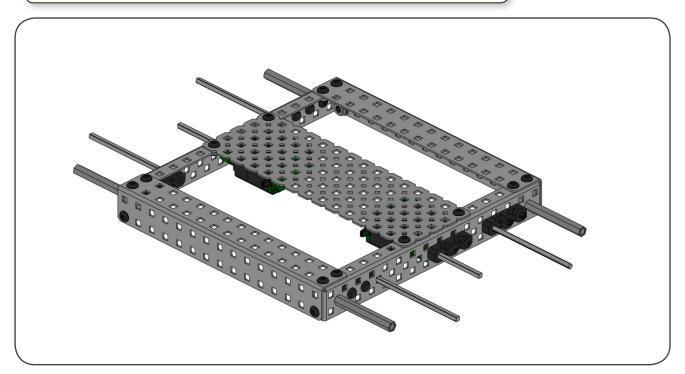




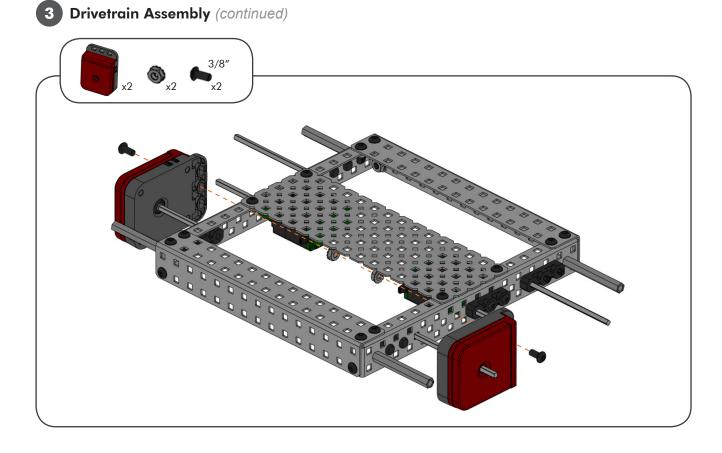


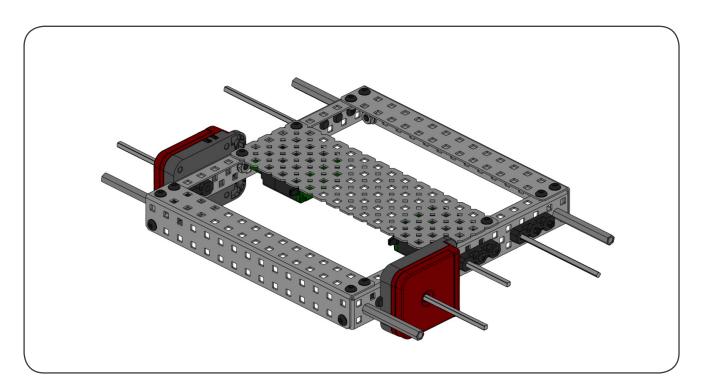
🚺 Building Tip - Shaft Length

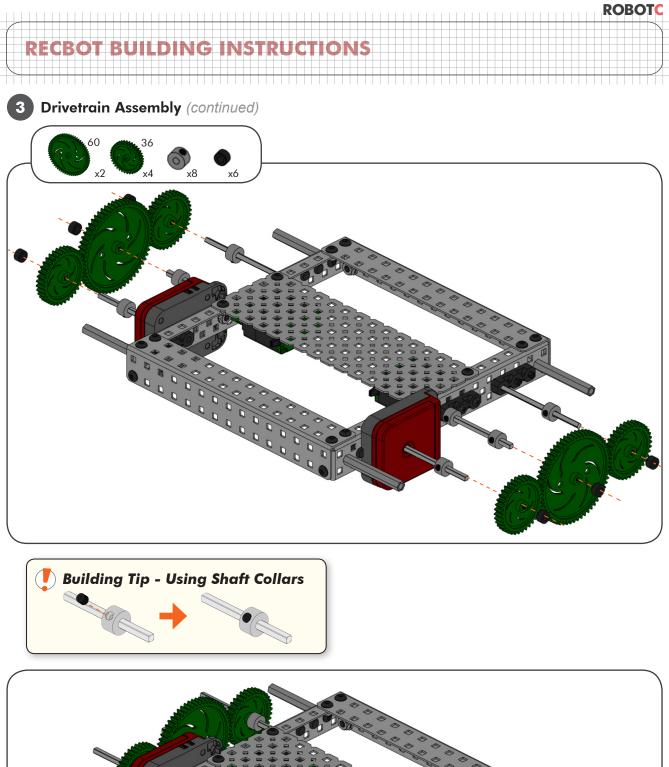
The shafts depicted above are the minimum usable lengths. Longer shafts, if available, can be used to provide some additional support in the drivetrain.

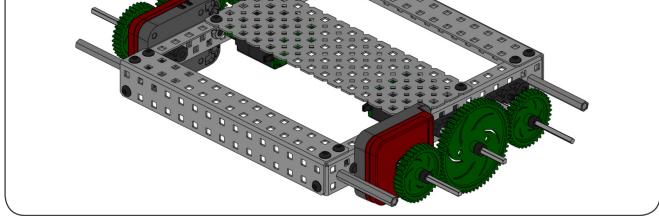


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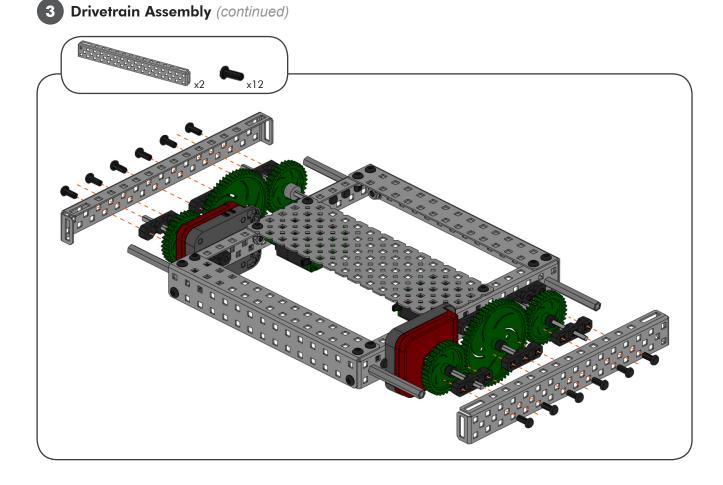


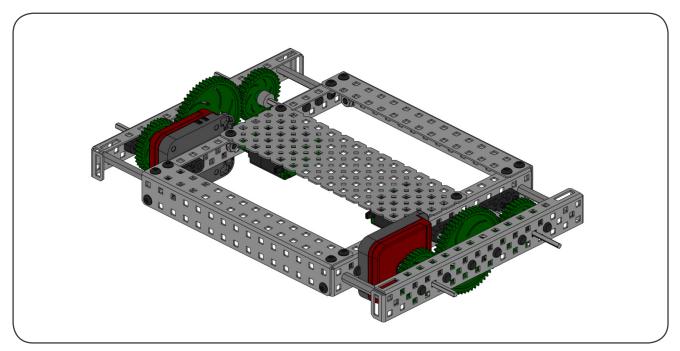




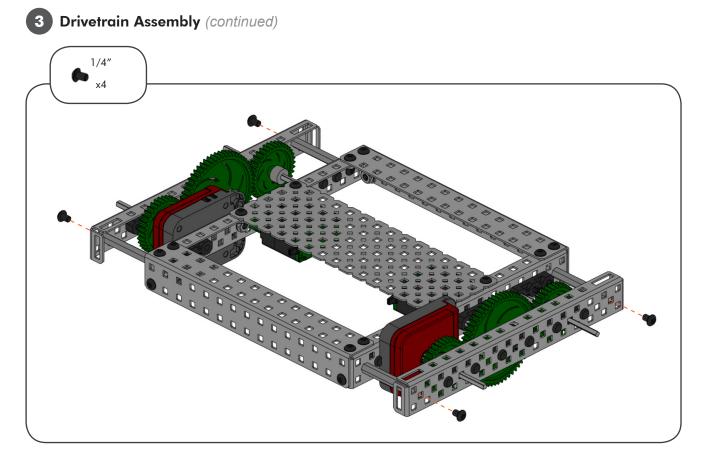
 $\ensuremath{\mathbb{C}}$ Carnegie Mellon Robotics Academy / For use with VEX* Robotics Systems

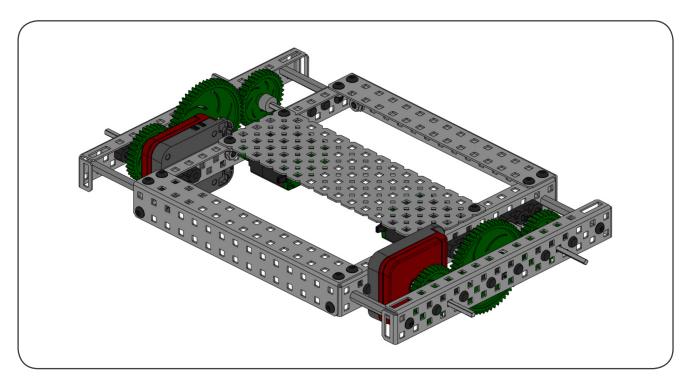
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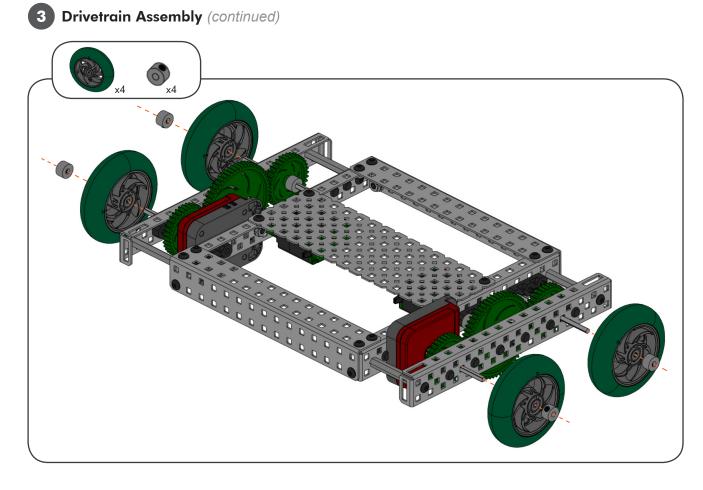


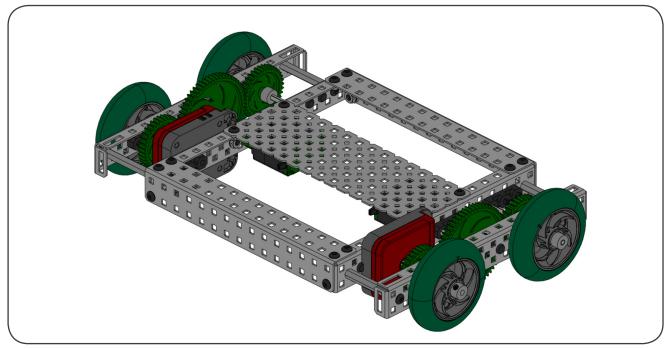
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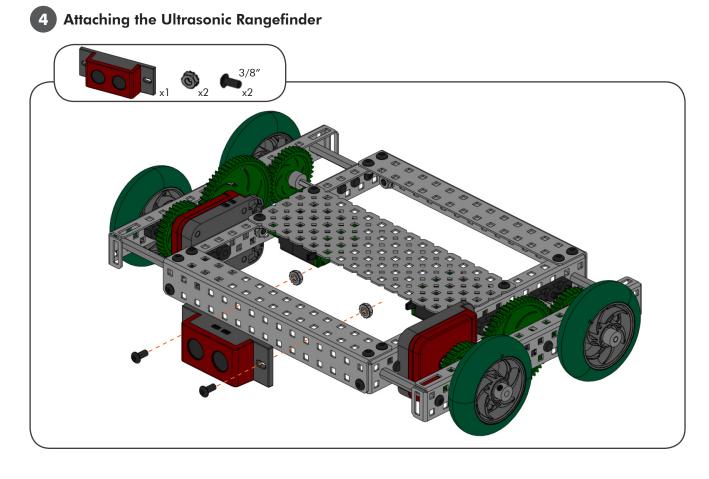


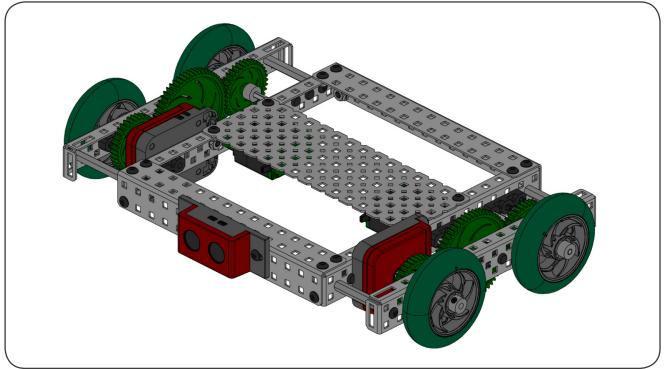






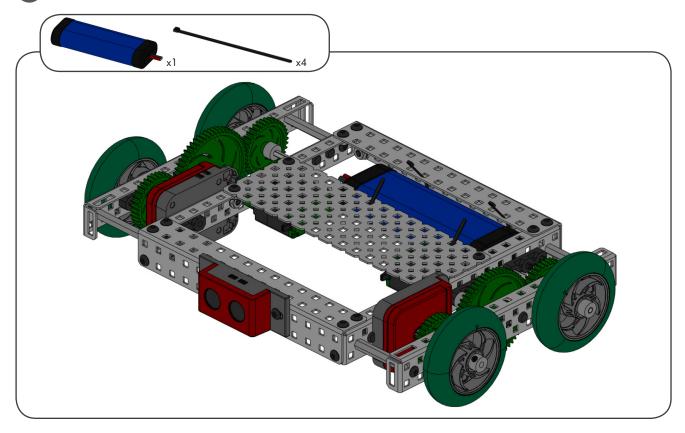
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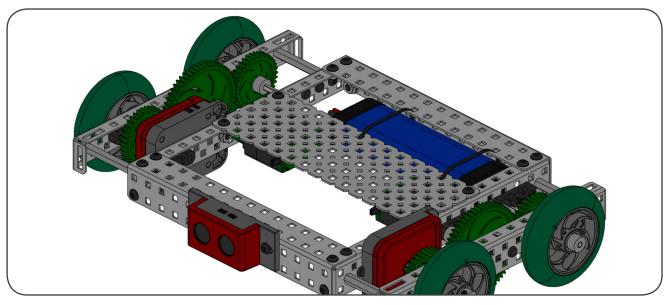








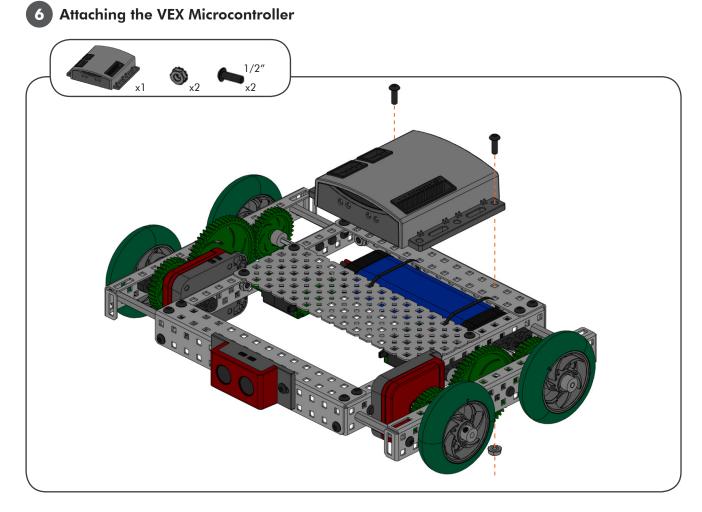


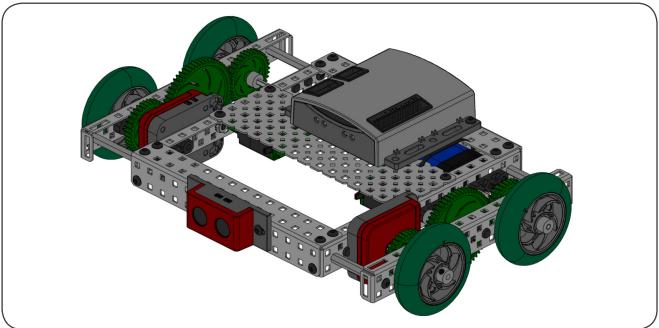


Building Tip - Using Wire Ties

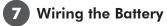
Multiple wire ties can be connected end-to-end to create a longer strand. Also, keeping the wire ties slightly loose around the battery will enable you to remove it for charging, but still hold it in place while the robot is moving.

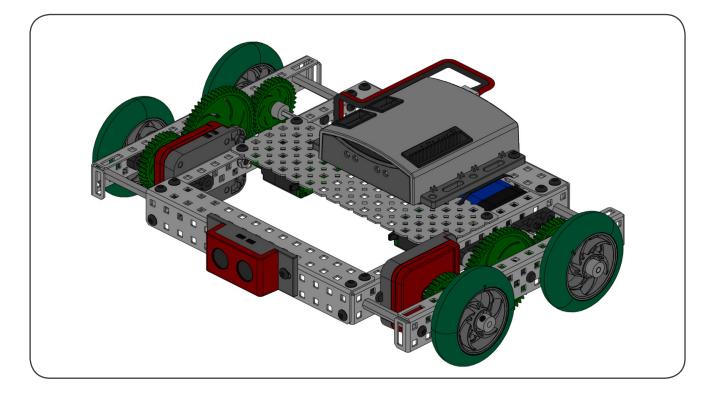


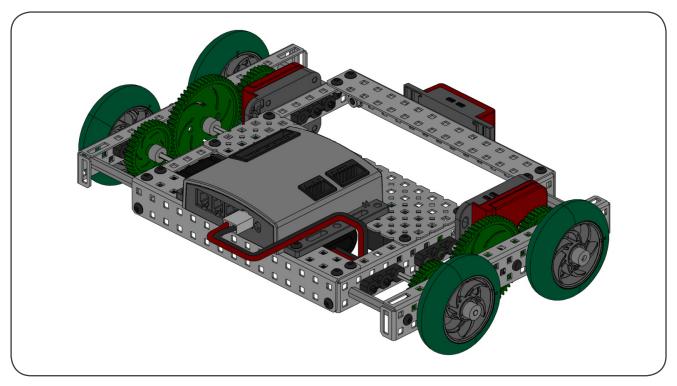




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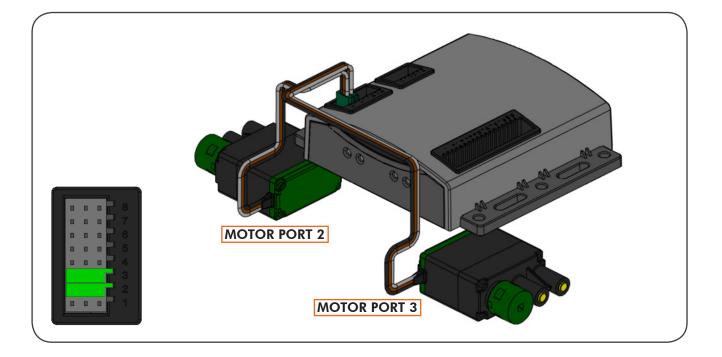


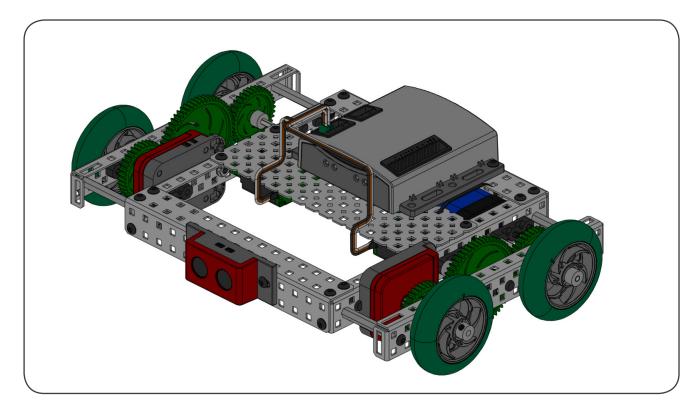






8 Wiring the Motors

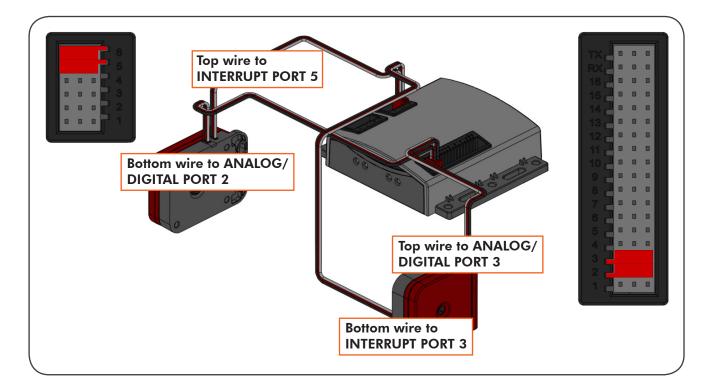


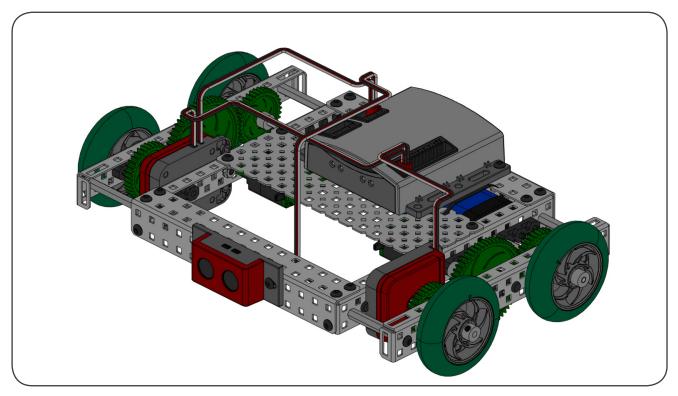




Wiring the Encoders

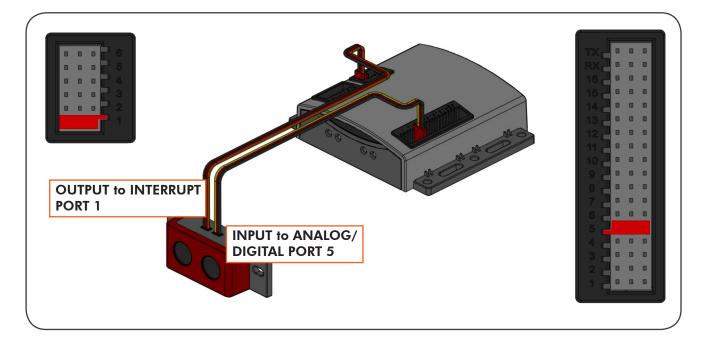
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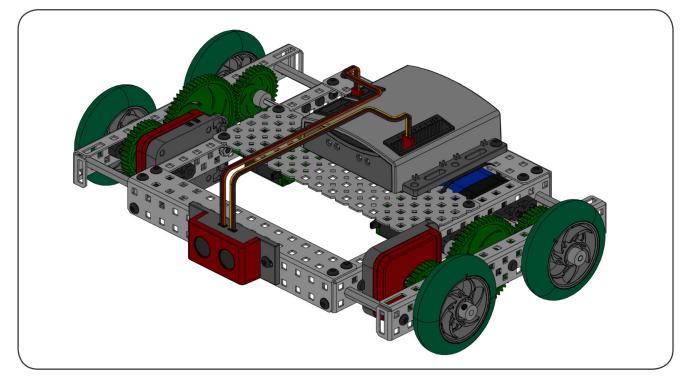












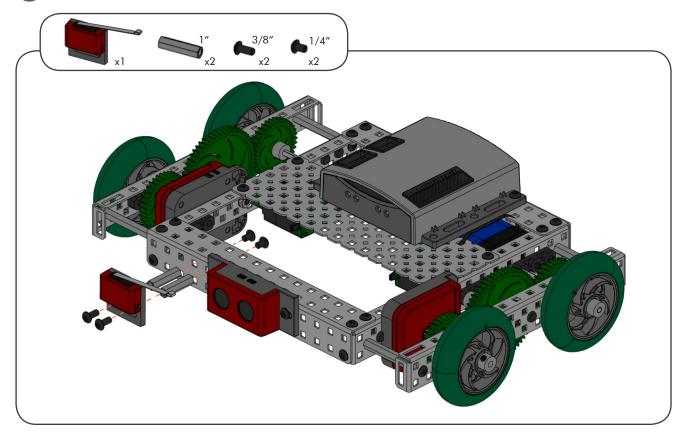
Information - Building Part I Complete

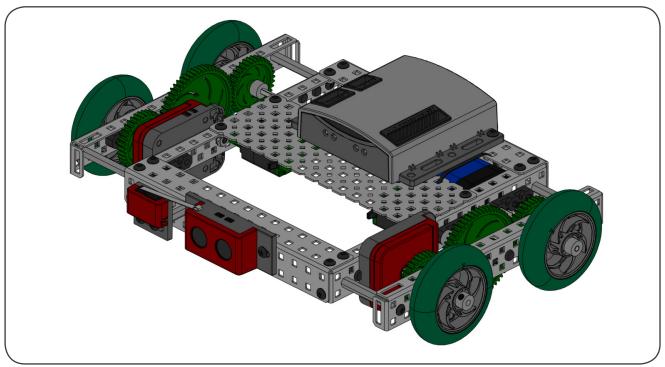
The robot is equipped to perform autonomous tasks based on timing, Encoder rotations, and Ultrasonic Rangefinder feedback. It's recommended that you wire tie any loose wires on your robot, keeping them clear of the drivetrain. Continue on through the remaining instructions to add a Limit Switch, robotic arm, and Potentiometer.

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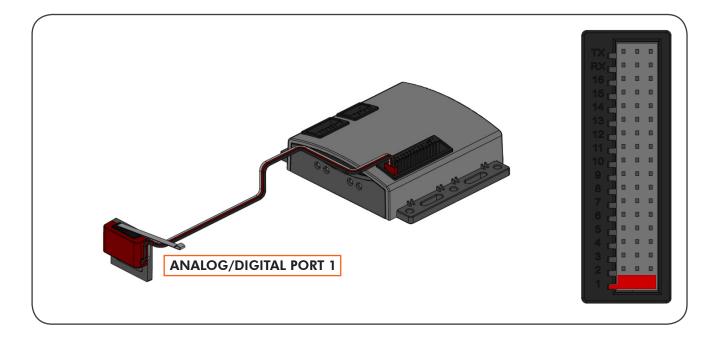
11 Attaching the Limit Switch

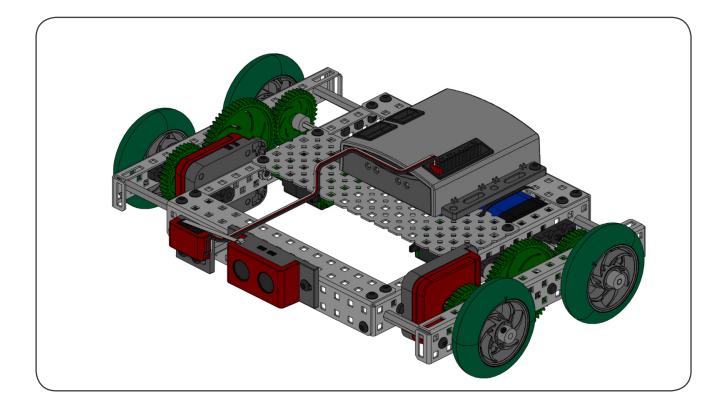






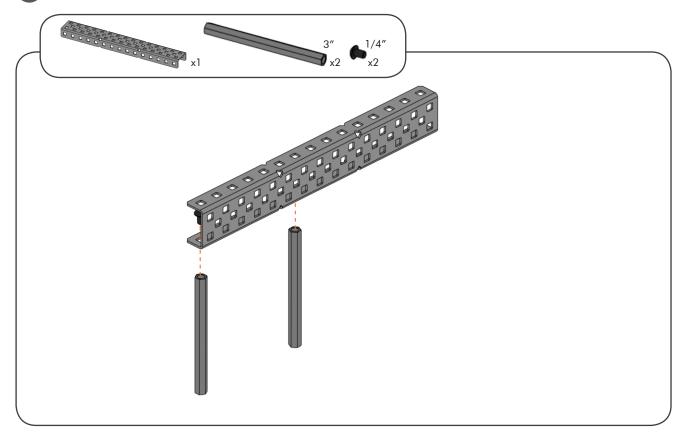


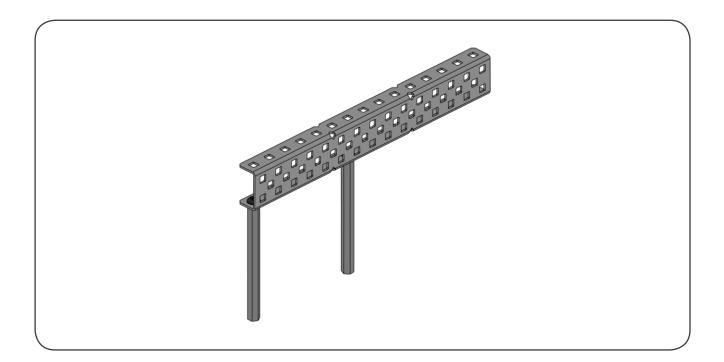






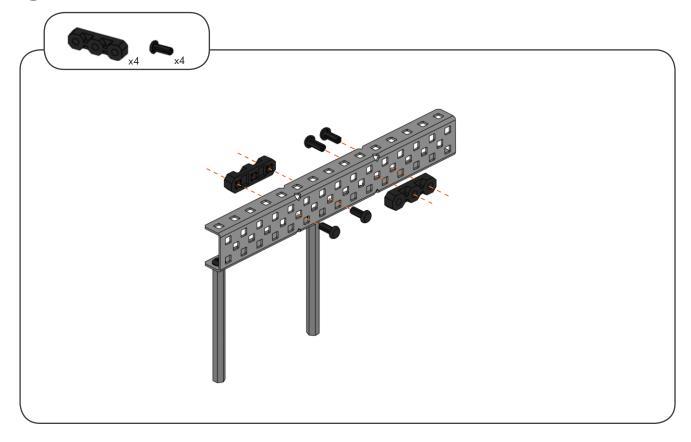


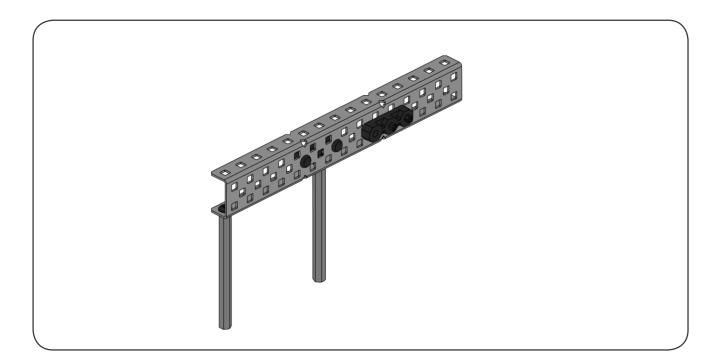




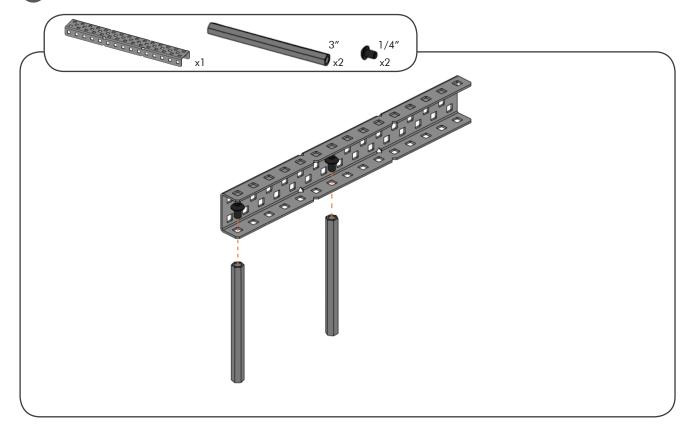
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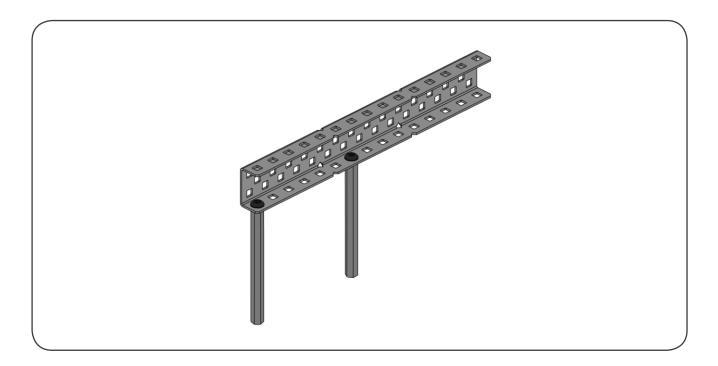




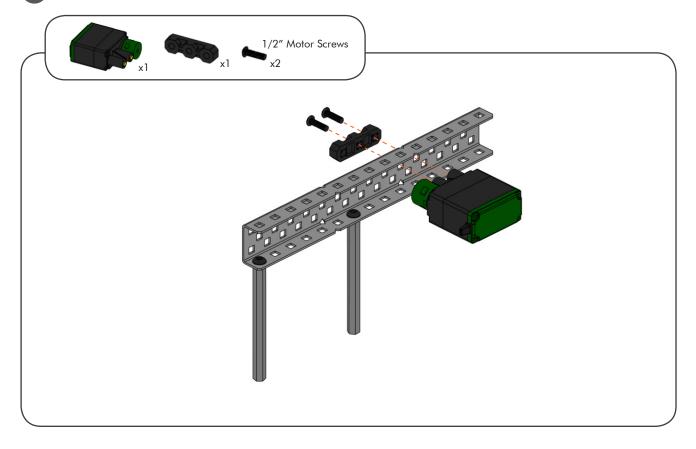


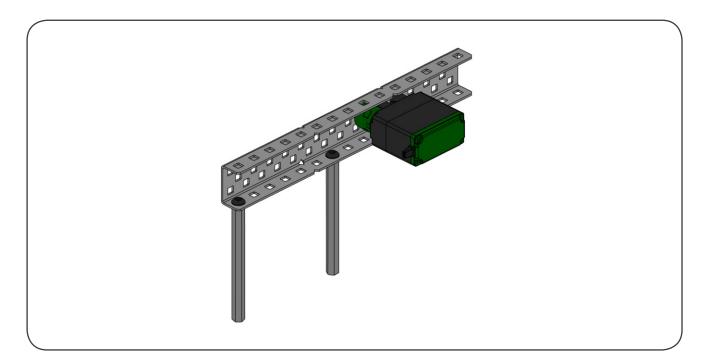






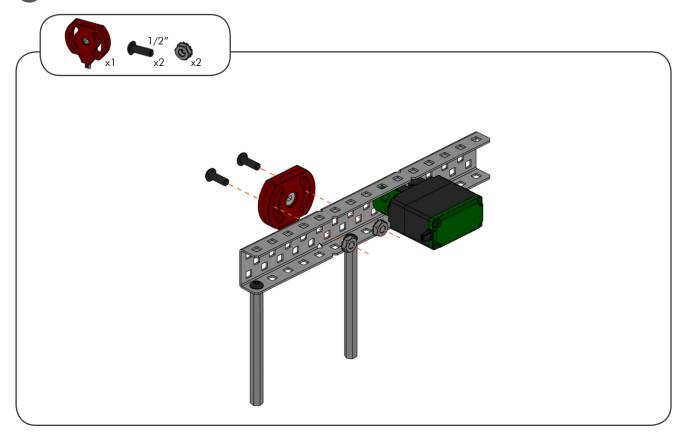


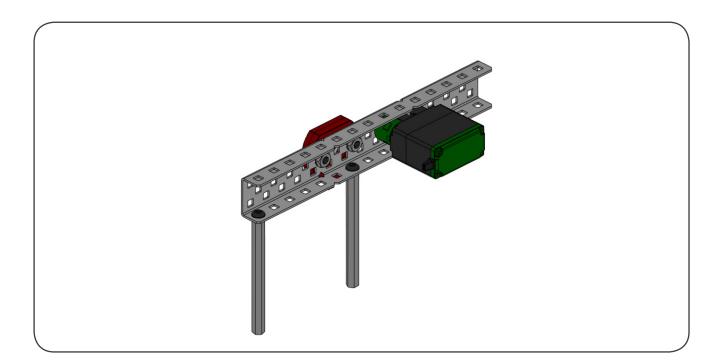




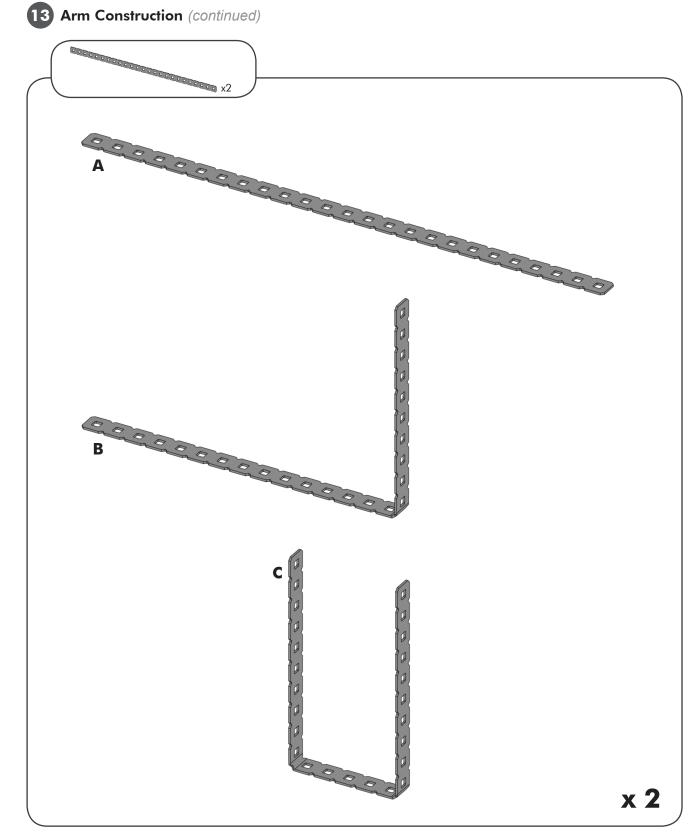












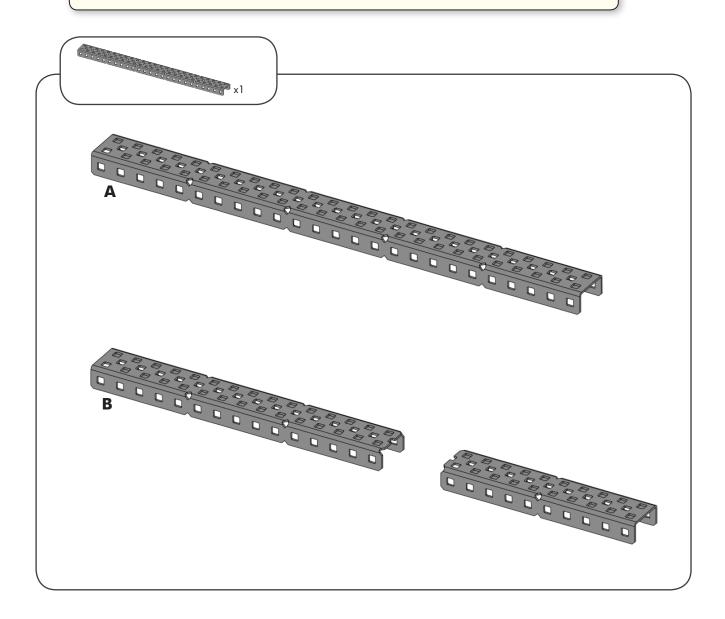




CAUTION - Cutting Tools

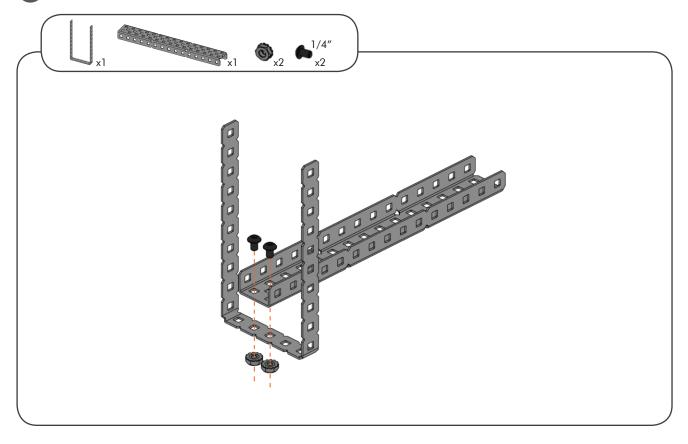
The following step involves cutting tools and permanent alterations to the materials in the VEX Kit. Make sure you have permission before continuing.

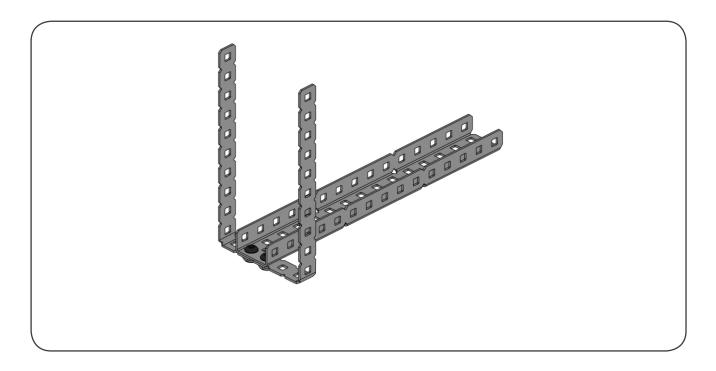
ALL APPLICABLE SAFETY PROCEDURES MUST BE OBSERVED WHILE PERFORMING THIS STEP. IF YOU ARE UNSURE ABOUT HOW TO USE THE TOOLS OR PERFORM THIS PROCEDURE SAFELY, DO NOT ATTEMPT THIS STEP ALONE. SEEK QUALIFIED ASSISTANCE BEFORE PROCEEDING.





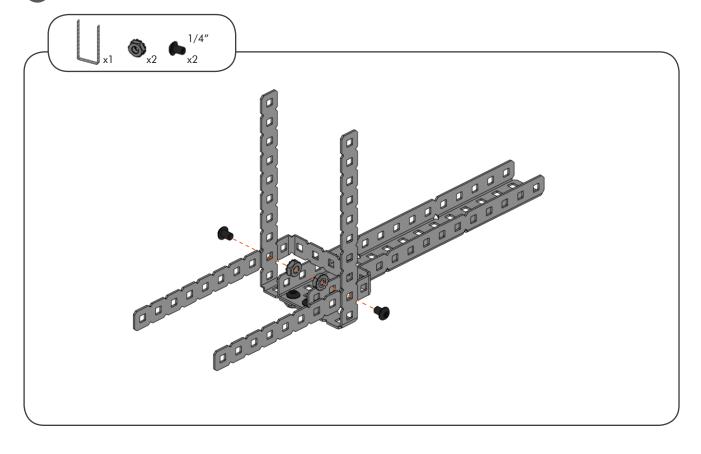


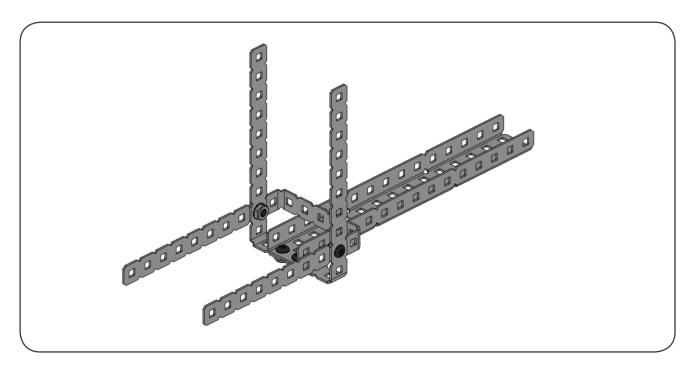




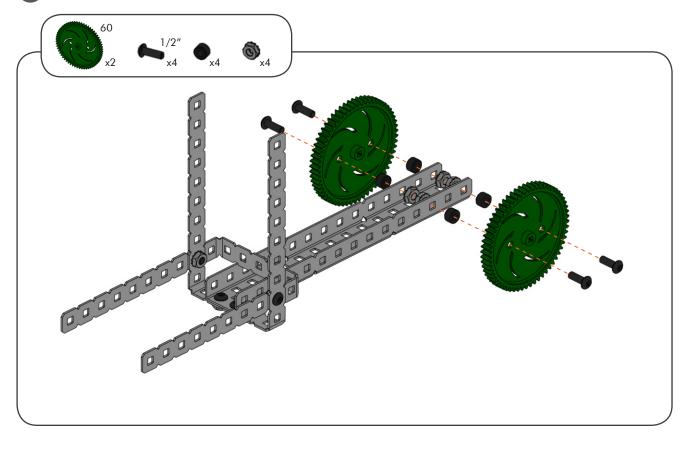


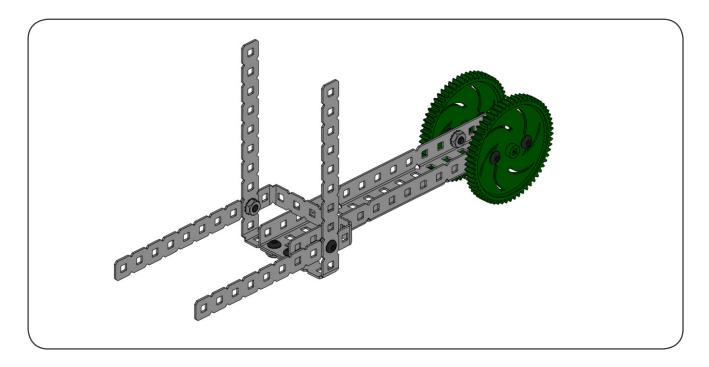
13 Arm Construction (continued)





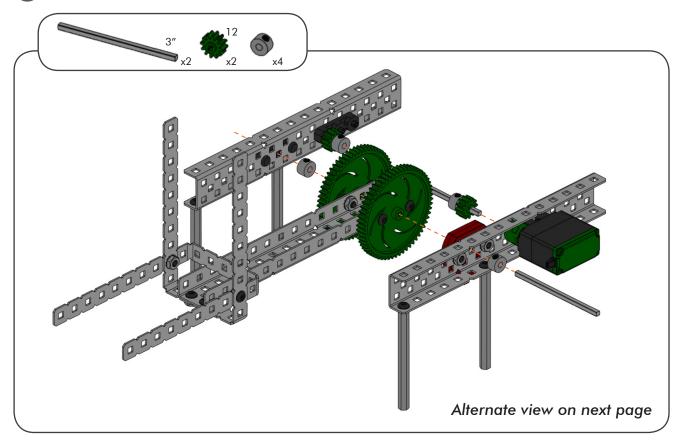
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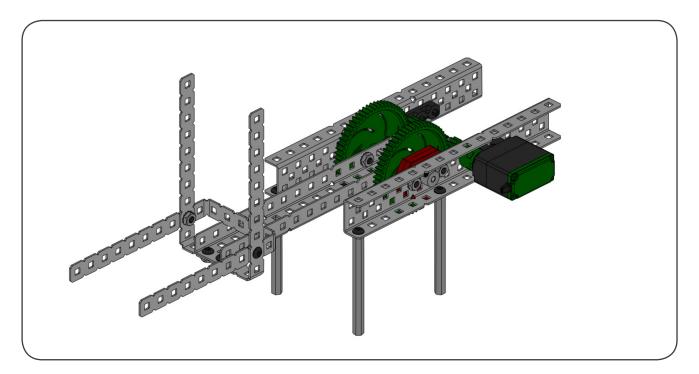




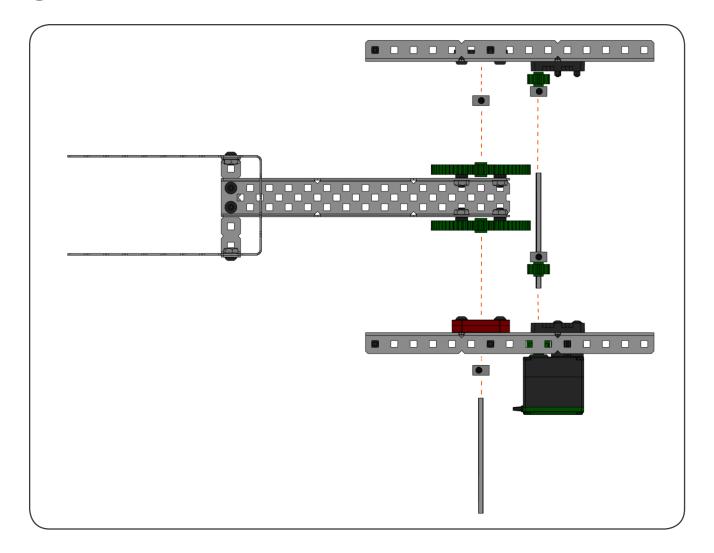


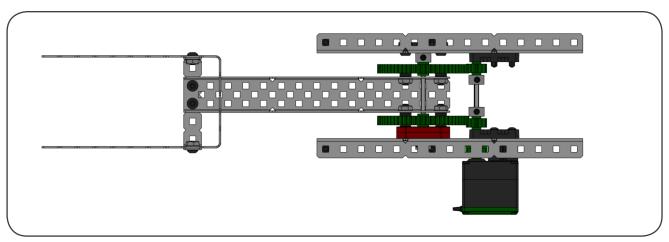




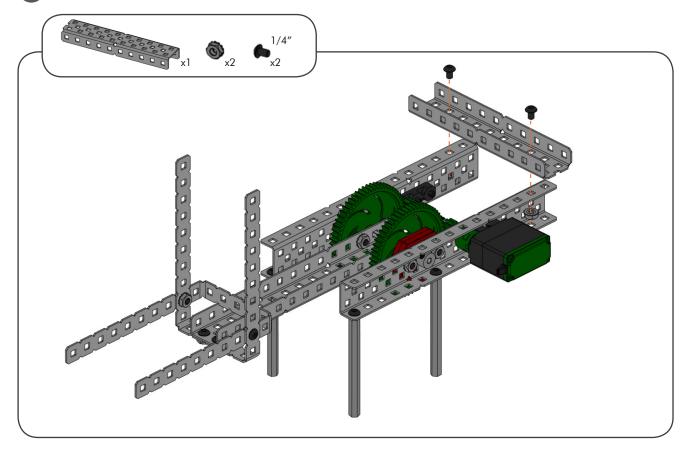


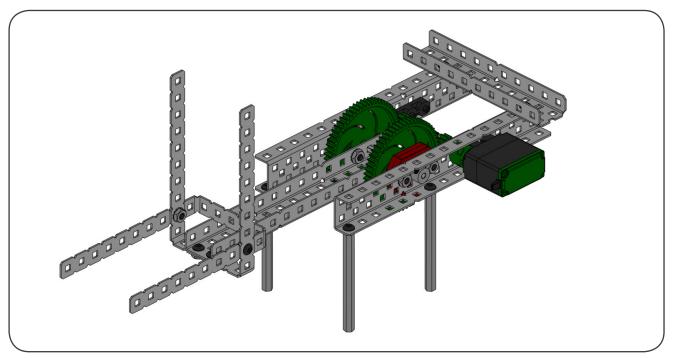






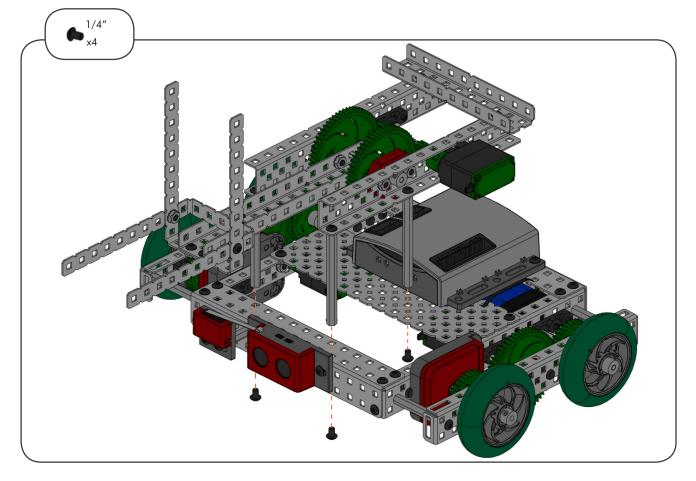


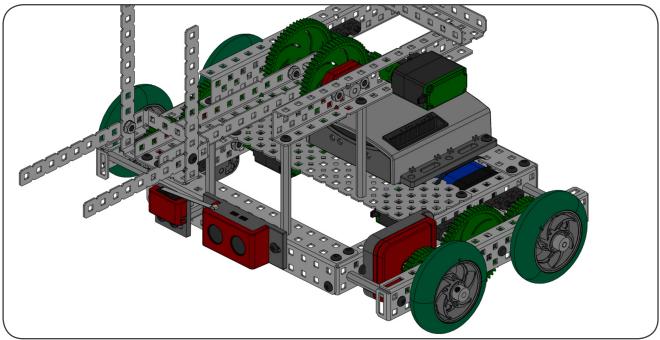




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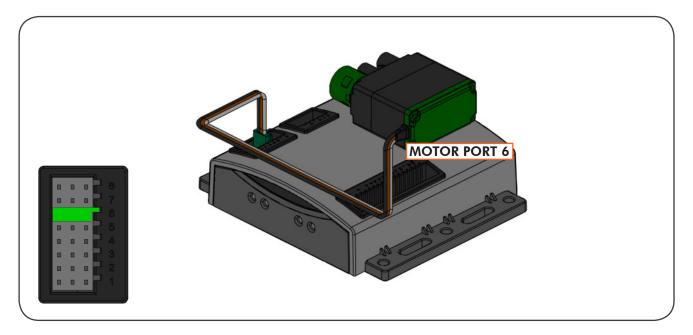


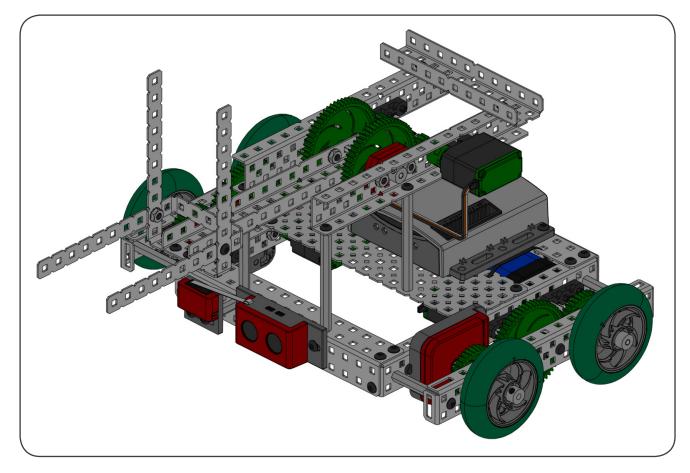






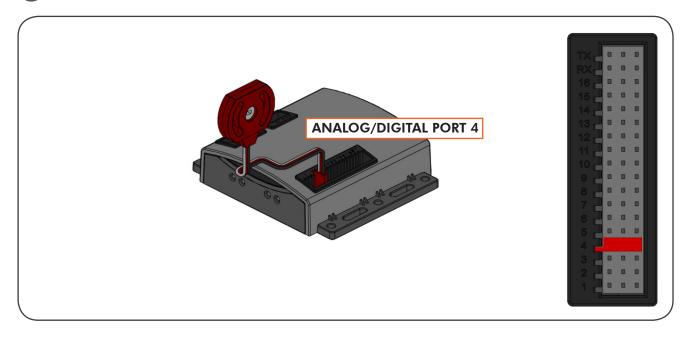


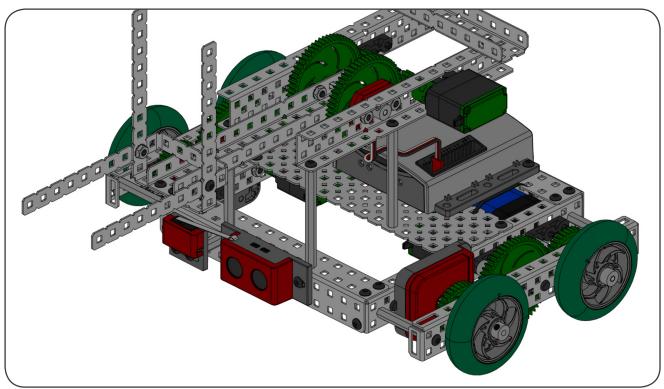












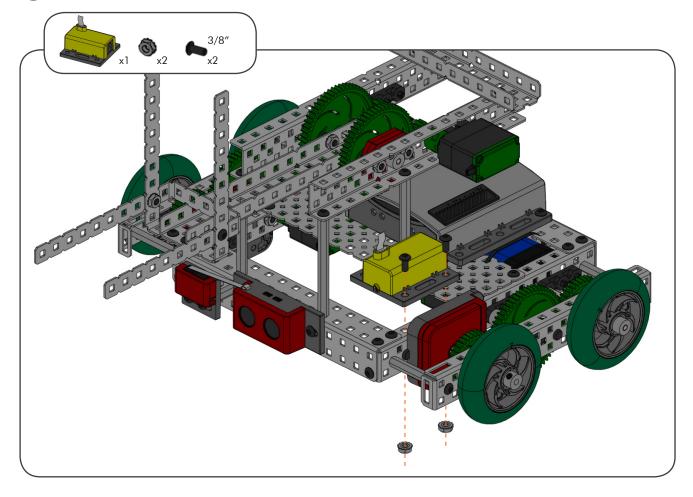
Information - Building Part 2 Complete

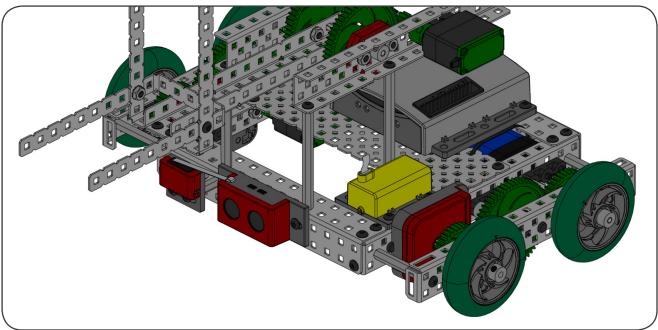
The robot is equipped to perform autonomous tasks that incorporate the arm. Continue on through the optional instructions to add the Receiver if you want enable remote control of the robot using the Radio Control Transmitter.

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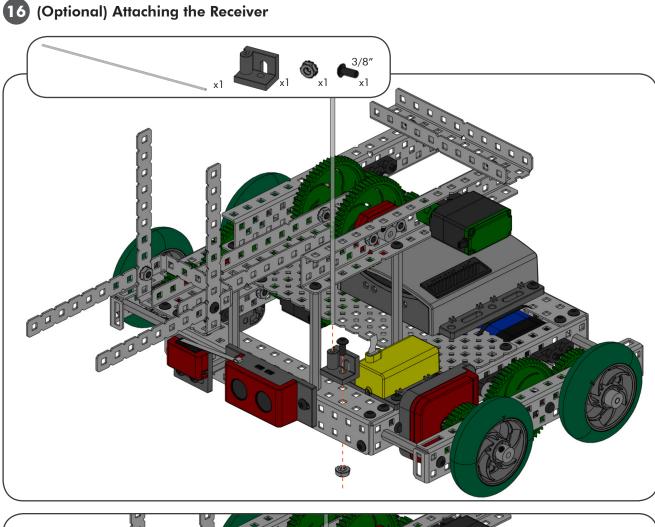


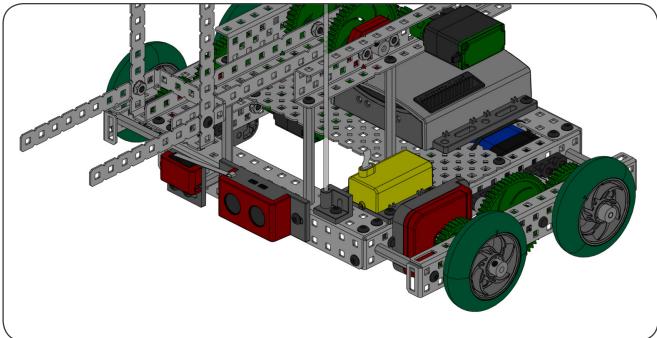
16 (Optional) Attaching the Receiver











ROI	BOTC



(Optional) Wiring the Receiver

